## PHYS4390-Assignment 2

## Due in Class on Wed, Feb 15, 2012 (Time allowed=two weeks)

## Show all working.

(1) (a) Is the following equation a legitimate tensor equation:

$$
x^{\mu}=y_{\mu} ?
$$

Explain your answer.
(b) Write out the matrix equation $A=B C$ using index notation.
(c) By manipulating dummy indices find an alternative expression for

$$
\left(A_{\mu \nu \gamma}+A_{\gamma \mu \nu}+A_{\nu \mu \gamma}\right) M^{\mu} N^{\nu} P^{\gamma}
$$

which only includes the tensor $A_{\mu \nu \gamma}$ multiplied by combinations of the other tensors.
(d) show that $\delta_{a}^{b} X^{a}=X^{b}$ and that $\delta_{a}^{b} X_{b}=X_{a}$.
(e) show that $\delta_{a}^{b} \delta_{b}^{c} \delta_{c}^{d}=\delta_{a}^{d}$.
(f) Write out the dot and cross products of two vectors using index notation (HINT: you will need more than just the vector components for one of these.)
(2) For a tensor, $R_{a b}$, and contravariant vector, $X^{a}$, verify or state whether the following are true/false
(a) (True/false) $X^{a} X^{b}=X^{b} X^{a}$
(b) (True/false) $R_{a b}=R_{b a}$
(c) (Verify) if $R_{a b}$ is antisymmetric then $R_{a a}=0$
(d) (Verify) if $R_{a b}$ is symmetric then $R_{a b} Y^{a b}=R_{a b} Y^{(a b)}$
(e) (Verify) if $R_{a b}$ is antisymmetric and $Y^{a b}$ is symmetric then $R_{a b} Y^{a b}=0$.
(f) You don't actually have to do this explicitly, but how would you go about showing the identity:

$$
\epsilon_{i j k} \epsilon_{i m n}=\delta_{j m} \delta_{k n}-\delta_{j n} \delta_{k m}
$$

(g) (Show) The symmetric part of a tensor can actually be separated into two further distinct components,
one component $\bar{T}^{a b}$ will have a trace of zero (i.e. the sum of the diagonal elements is zero), while the other component $\hat{T}^{a b}$ will be the identity (i.e. $\delta^{a b}$ ) multiplied by something. (HINT: The fact that $\bar{T}^{a b}$ has zero trace will allow you determine what the factor that multiplies the identity is.)
(3) (a) Compute the Lie Brackets of the vector fields

$$
\begin{aligned}
\mathbf{V}_{1} & =z \frac{\partial}{\partial y}-y \frac{\partial}{\partial z} \\
\mathbf{V}_{2} & =-z \frac{\partial}{\partial x}+x \frac{\partial}{\partial z} \\
\mathbf{V}_{3} & =y \frac{\partial}{\partial x}-x \frac{\partial}{\partial y}
\end{aligned}
$$

(b) Use the results you get to give a one line proof of the Jacobi identity for these vectors.
(4) Consider coordinate triplets which lie on a sphere of radius 1 centered on the origin of a Cartesian coordinate system. For these coordinates we will define charts that map the two dimensional surface to the Euclidean plane by,

$$
M_{N}(x, y, z)=\left(\frac{x}{1+z}, \frac{y}{1+z}\right)
$$

$$
M_{S}(x, y, z)=\left(\frac{x}{1-z}, \frac{y}{1-z}\right) .
$$

(a) The maps are defined everywhere except two points - which ones?
(b) Since the charts overlap and map the unit sphere into the Euclidean plane, $M_{N} \circ M_{S}^{-1}$ on a point (u,v) must represent a smooth mapping of the plane from itself to itself (i.e. a map from ( $u, v$ ) to ( $\left.u^{\prime}, v^{\prime}\right)$ ). (HINT: Calculate $M_{S}^{-1}$ first by looking at how the pair ( $\mathrm{u}, \mathrm{v}$ ) maps back into three dimensions.)
(5) Suppose that $B^{a_{1} \ldots a_{r}}{ }_{b_{1} \ldots b_{s}}$ is a type(r,s) tensor field. Calculate how it's partial derivative (with respect to an index $c$ ) transforms under coordinate changes.
(6) (a) Show that the Lie derivative on functions and vector fields (so you'll need to consider two proofs) obeys,

$$
\left[L_{X}, L_{Y}\right]=L_{[X, Y]},
$$

for vector fields X \& Y.
(b) Prove the Jacobi identity for Lie derivatives for three vector fields $\mathrm{X}, \mathrm{Y}, \mathrm{Z}$ (on both functions and vector fields).
(c) Show that the Lie derivative obeys,

$$
L_{X}(f Y)=\left(L_{X} f\right) Y+f\left(L_{X} Y\right)
$$

for vector fields X and Y and a function $f$.
(7) Assuming that

$$
\nabla_{c} X^{a}=\partial_{c} X^{a}+\Gamma^{a}{ }_{b c} X^{b}
$$

and that

$$
\nabla_{a} \phi=\partial_{a} \phi,
$$

where $\phi$ is a scalar, show that for the covariant derviative to be Liebniz then

$$
\nabla_{c} X_{a}=\partial_{c} X_{a}-\Gamma^{b}{ }_{a c} X_{b} .
$$

(8) Show that the connection coefficients $\Gamma^{a}{ }_{b c}$ are not tensors.

