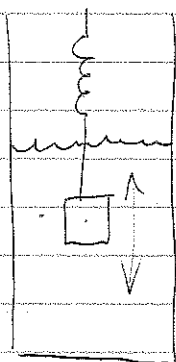


Decay of free vibrations

- Vibrations do not continue forever
- The loss of energy is related to the concept of damping

Where does the energy go?



Consider spring-mass system in water

- Where does the energy go?

Into water motion

- If you can hear it, it's losing energy!

Resistive forces are often $\propto v, v^2$ so that

$$\vec{F}_d = -b_1 \vec{v} - b_2 v^2 \hat{v}$$

* $v \ll \frac{b_1}{b_2}$

In many cases the dependence on the v^2 term is small at low velocities*, so we often write

$$\vec{F}_d \approx -b_1 \vec{v} \approx -b_1 \vec{v} \approx b \vec{v} \quad (\text{dropping subscript})$$

This means the equation of motion is now:

$$F = m\ddot{x} = -kx - b\dot{x}$$

Same as before

damping force resists motion

Thus $m\ddot{x} = -kx - b\dot{x}$

$$\Rightarrow \ddot{x} + \frac{b}{m} \dot{x} + \frac{k}{m} x = 0$$

Let $\gamma = \frac{b}{m}$ $\omega_0^2 = \frac{k}{m}$ Then

$$\ddot{x} + \gamma \dot{x} + \omega_0^2 x = 0$$

So ω_0^2 is analogous to $\omega = \frac{k}{m}$ for the undamped case.

Units: Interesting to think about the units of γ & ω_0 .

$$\omega_0^2 \equiv \frac{k}{m} = \frac{F/x}{m} \Rightarrow \text{Units are } \frac{MLT^{-2}/L}{M} = T^{-2}$$

So ω_0 has units of frequency

$$\text{For } \gamma: \gamma \equiv \frac{b}{m} = \frac{F/v}{m} \Rightarrow \text{units are } \frac{MLT^{-2}/LT^{-1}}{M} = T^{-1}$$

So γ also has units of frequency

$\Rightarrow$ It tells us something about time dependences in the solution.

Let's solve the equation of motion. Use the complex exponential approach where we take the real part of z as x . Firstly, consider

$$\ddot{z} + \gamma \dot{z} + \omega_0^2 z = 0 \quad \text{where } z = Ae^{j(p t + \alpha)}$$

$$\text{Then } \dot{z} = j p A e^{j(p t + \alpha)} = j p z$$

$$\ddot{z} = j^2 p^2 z = -p^2 z$$

Substituting back into equation:

$$\{-p^2 + j p \gamma + \omega_0^2\} A e^{j(p t + \alpha)} = 0$$

To be true at all times bracket must be zero, i.e.

$$-p^2 + j p \gamma + \omega_0^2 = 0$$

But This is a complex equation with real & imaginary parts.

Note we can't set $p=0$ as then there is no time evolution.

If $\gamma=0$ then we don't have any damping, so it must be non-zero, + it is real

Together, these imply p must have real & imaginary parts (ω_0 is real).

Thus set $p = n + js$. Then for the imaginary part:

$$p^2 = n^2 + 2jns - s^2$$

$$\text{So } -p^2 + jp\gamma + \omega_0^2 = 0 \quad \text{gives}$$

$$-n^2 - 2jns + s^2 + jn\gamma - s\gamma + \omega_0^2 = 0 \quad \text{--- (A)}$$

$$\text{Hence Imaginary part is: } (-2ns + n\gamma)j = 0$$

$$\Rightarrow -2ns + n\gamma = 0$$

$$\text{Cancelling } n \text{ we get } s = \frac{\gamma}{2}$$

For the real part we take all non-imaginary parts from (A) & set to zero.

$$-n^2 + s^2 - s\gamma + \omega_0^2 = 0$$

Then if $s = \frac{\gamma}{2}$ we find

$$n^2 = \frac{\gamma^2}{4} - \frac{\gamma^2}{2} + \omega_0^2 = -\frac{\gamma^2}{4} + \omega_0^2 = \omega_0^2 - \frac{\gamma^2}{4}$$

$$\text{Thus we have shown } p = \omega_0^2 - \frac{\gamma^2}{4} + j\frac{\gamma}{2}$$

What does this mean in terms of the formulae for z ?

$$\begin{aligned}
 \text{Since } z &= A e^{j(pt+\alpha)} && \text{sub in } p = \gamma + j\omega \text{ first} \\
 &= A e^{j(\gamma t + j\omega t + \alpha)} \\
 &= A e^{\gamma t} e^{j\omega t} e^{j\alpha} \\
 &= A e^{-\gamma t} e^{j(\omega t + \alpha)} \\
 &= A e^{-\gamma t} \{ \cos(\omega t + \alpha) + j \sin(\omega t + \alpha) \}
 \end{aligned}$$

So now if we take the real part:

$$x = \operatorname{Re} z = A e^{-\gamma t} \cos(\omega t + \alpha)$$

& substituting for γ & ω we get

$$x = A e^{-\gamma t/2} \cos\left(\left[\omega_0^2 - \frac{\gamma^2}{4}\right]^{1/2} t + \alpha\right)$$

$$\text{let } \omega^2 = \omega_0^2 - \frac{\gamma^2}{4} \text{ then}$$

$$x = \underbrace{A e^{-\gamma t/2}}_{\text{Exponential decay modifier}} \underbrace{\cos(\omega t + \alpha)}_{\text{SHM term}}$$

(note $\gamma > 0$ from its definition)

Note: both γ & ω are specified since by definition (see 6.2)

$$\omega_0 = \frac{k}{m} \quad \gamma = \frac{b}{m} \quad \& \quad \omega^2 = \frac{k}{m} - \frac{b^2}{4m^2}$$

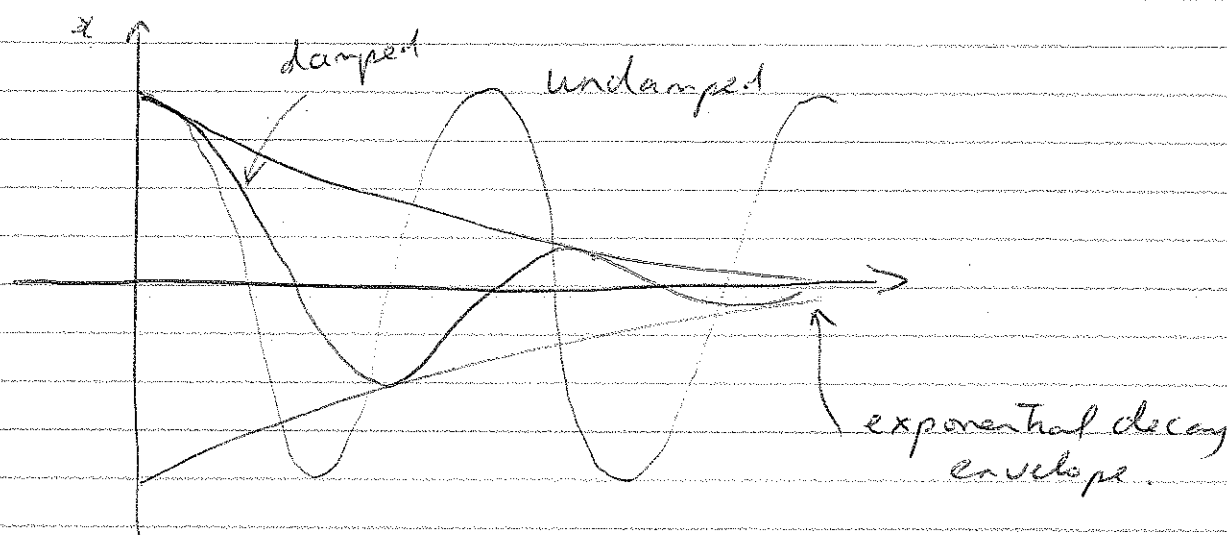
So given mass, spring constant & resistive force we can evaluate both the decay time exponent & the frequency of oscillation.

Q: Does damped oscillator oscillate faster or slower than undamped?

$$\omega^2 = \omega_0^2 - \frac{\gamma^2}{4} = \frac{k^2}{m^2} - \frac{b^2}{4m^2} \quad \text{so slower}$$

makes sense

Thus the picture we get is as follows:



In the complex plane we can think of a spiral:

