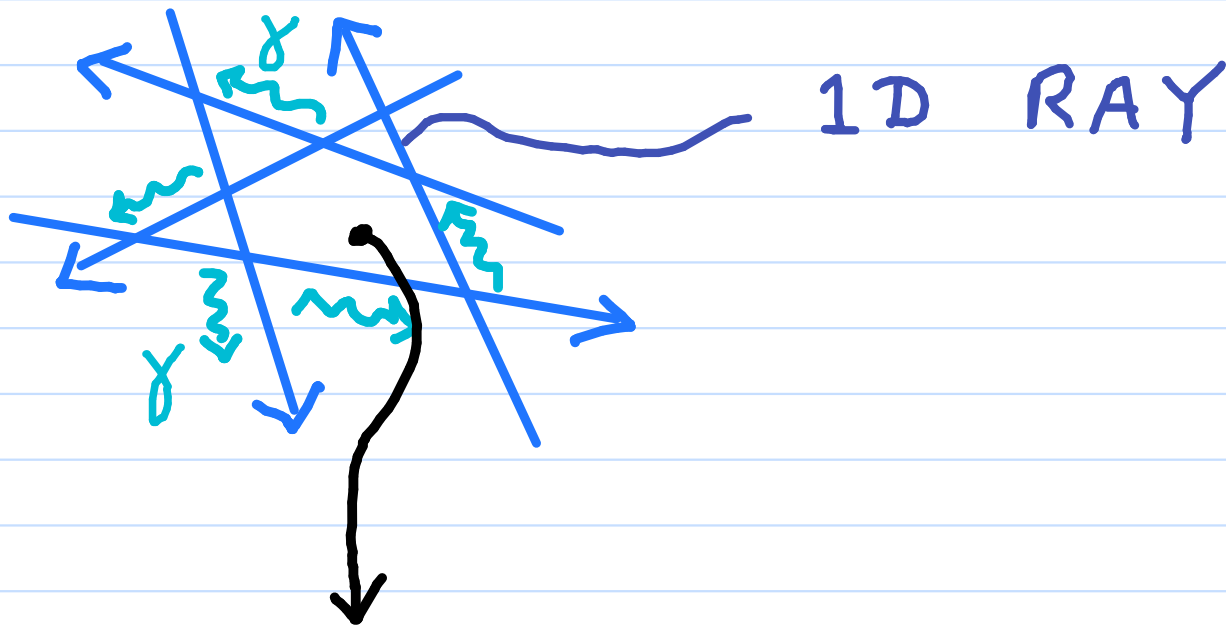
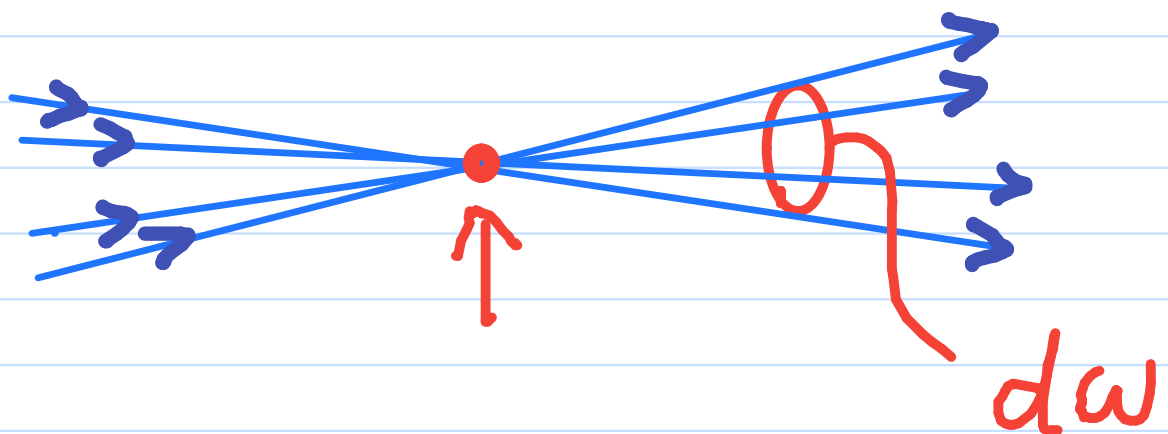


# RADIATION

## GENERAL 3D RADIATION FIELD:

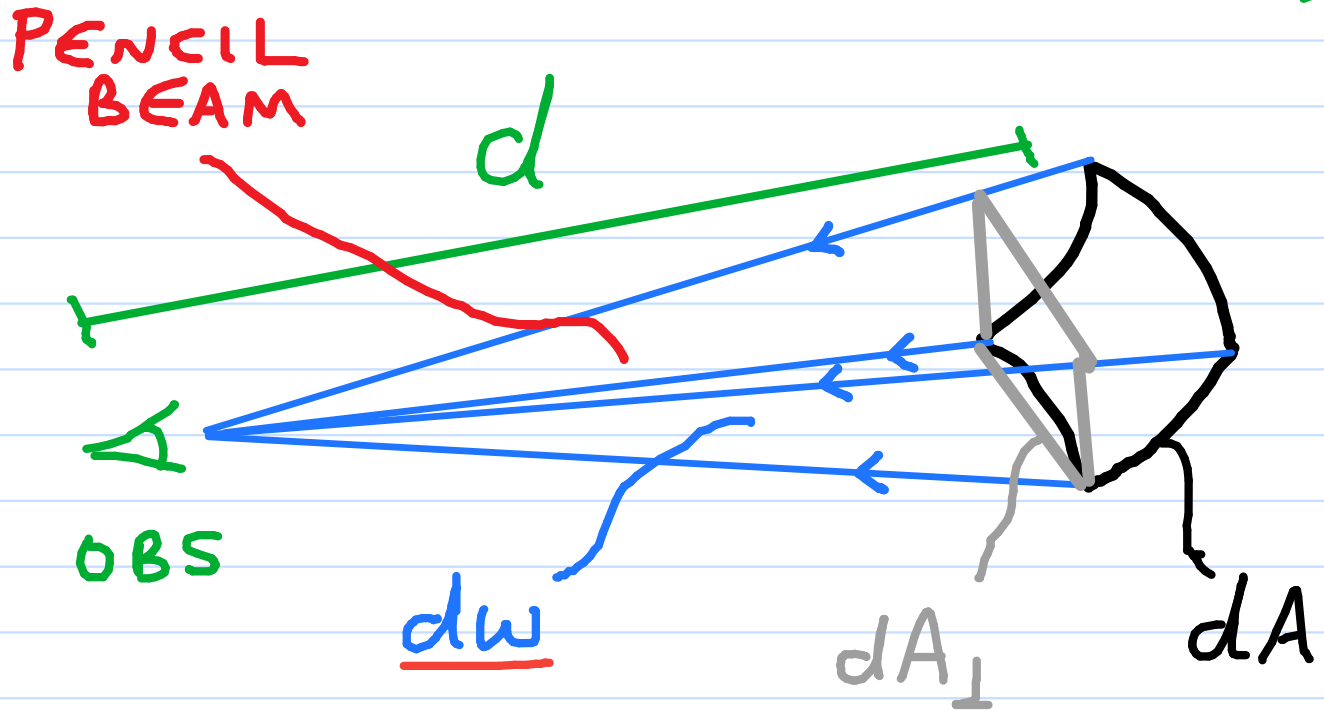


## PENCIL BEAM:



SUBTENDS SOLID ANGLE dw

SOLID ANGLE,  $\omega$  (STERADIANS, "STER")



IF  $dA_{\perp} \ll d^2$ :

2D SMALL-ANGLE APPROX:

$$d\omega \approx \frac{dA_{\perp}}{d^2}$$

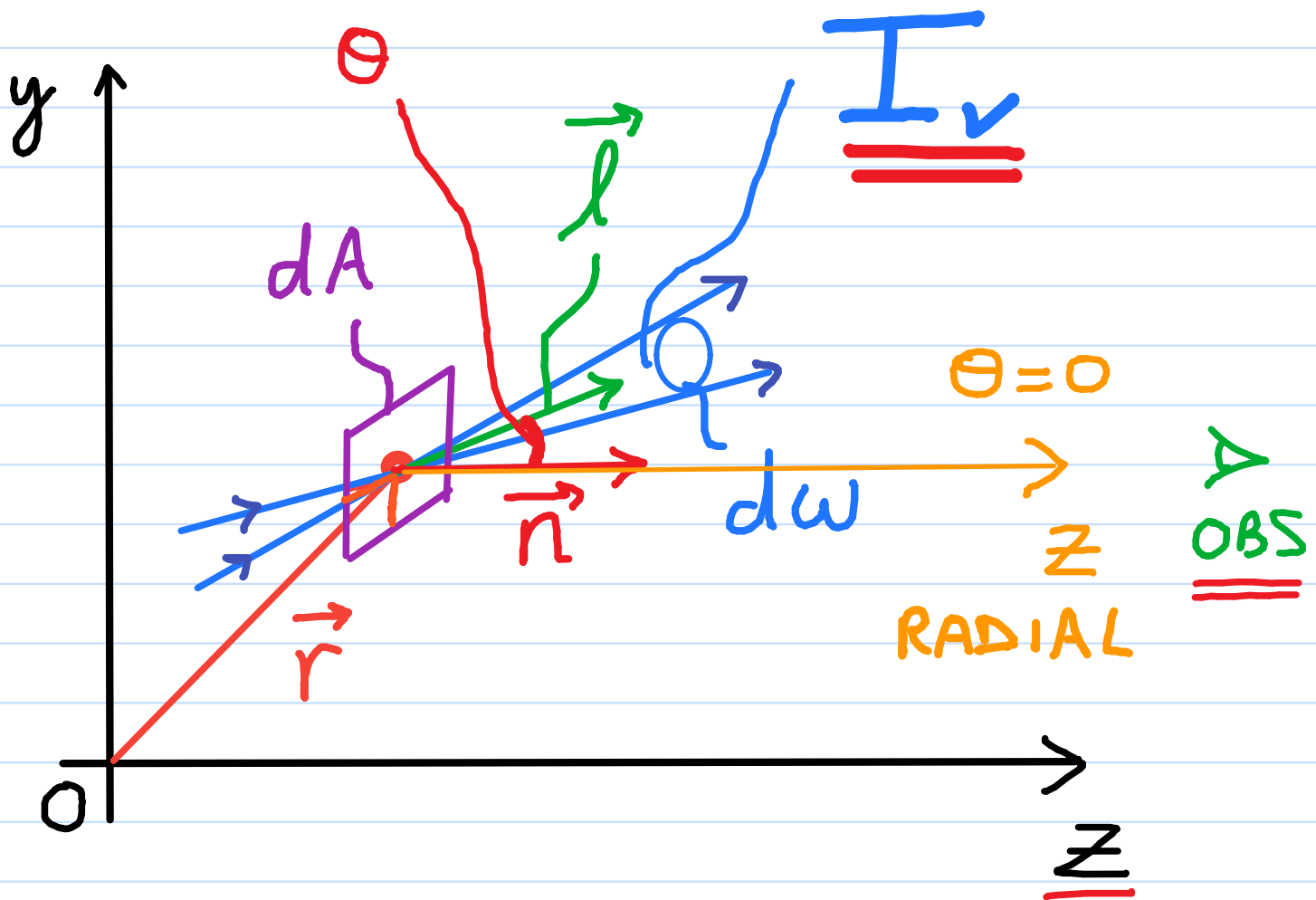
$$0 \leq \omega \leq 4\pi \text{ STER}$$

# RADIATION AMOUNT:

$$I_\nu, J_\nu, E_\nu, P_\nu, \mu_\nu$$

MONOCHROMATIC SPECIFIC INTENSITY

$$\underline{I}_\nu(\vec{r}, \vec{l}, t, \nu) \quad (\text{erg/s/cm}^2/\underline{\text{STER}}/\text{Hz})$$



GEOM. PROJECTION FACTOR:

$$\vec{l} \cdot \vec{n} = \vec{l} \cdot \hat{k} = \cos \theta \equiv \underline{\underline{\mu}}$$

$dE_\nu$  = RADIATION  $E$  IN BEAM  
CROSSING  $dA$  IN FREQ.

INTERVAL  $\nu$  TO  $\nu + d\nu$  IN  
TIME INTERVAL  $dt$  (erg) :

$$dE_\nu(\vec{r}, \vec{l}, t, \nu) \\ \equiv \underline{I_\nu}(\vec{r}, \vec{l}, t, \nu) dt \{dA (\vec{n}_l \cdot \vec{l})\} d\omega d\nu \\ \cos\theta = \mu$$

$$= I_\nu(\vec{r}, \vec{l}, t, \nu) dt (\underline{\mu} dA) d\omega d\nu$$

$$\therefore I_\nu \equiv \frac{dE_\nu}{dt (\mu dA) d\omega dt}$$

$$(\text{erg/s/cm}^2/\text{STER/Hz})$$

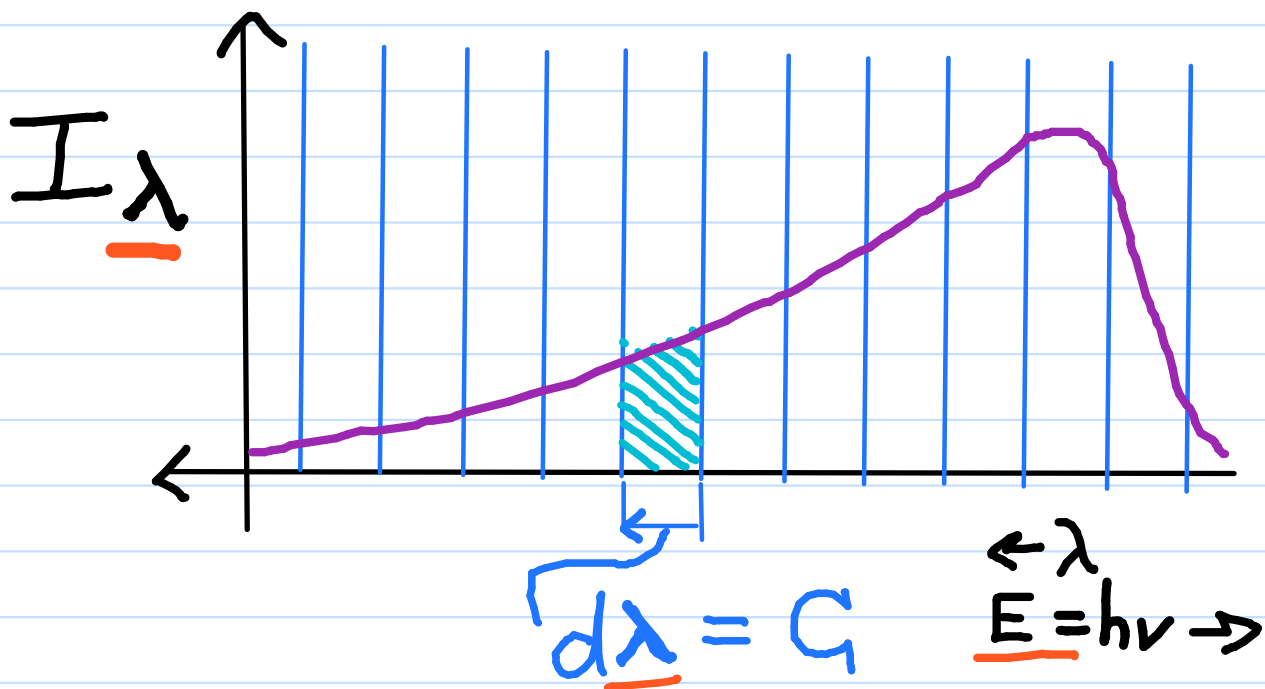
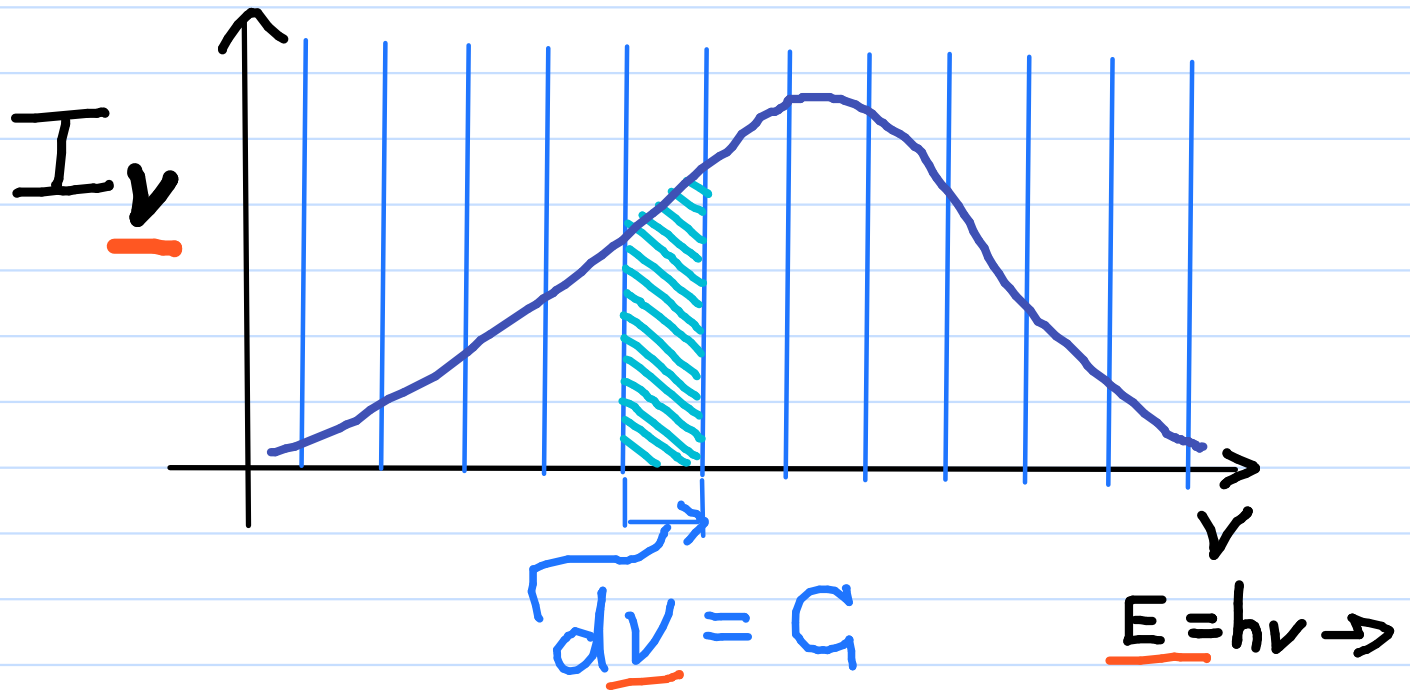
$dE_\lambda$  = RADIATION  $E$  IN BEAM  
 CROSSING  $dA$  IN WAVELENGTH  
 INTERVAL  $\lambda$  TO  $\lambda + d\lambda$  IN  
 TIME INTERVAL  $dt$  (erg):

$$dE_\lambda(\vec{r}, \vec{l}, t, \lambda) \\ \equiv I_\lambda(\vec{r}, \vec{l}, t, \lambda) dt (\mu dA) d\omega d\lambda$$

$$I_\lambda \text{ (erg/s/cm}^2\text{/STER/nm)}$$

$$I_\lambda = \left| \frac{d\nu}{d\lambda} \right| I_\nu = \frac{c}{\lambda^2} I_\nu$$

CONTINUOUS MONOCHROMATIC  
(SPECTRAL) I DISTRIBUTIONS:

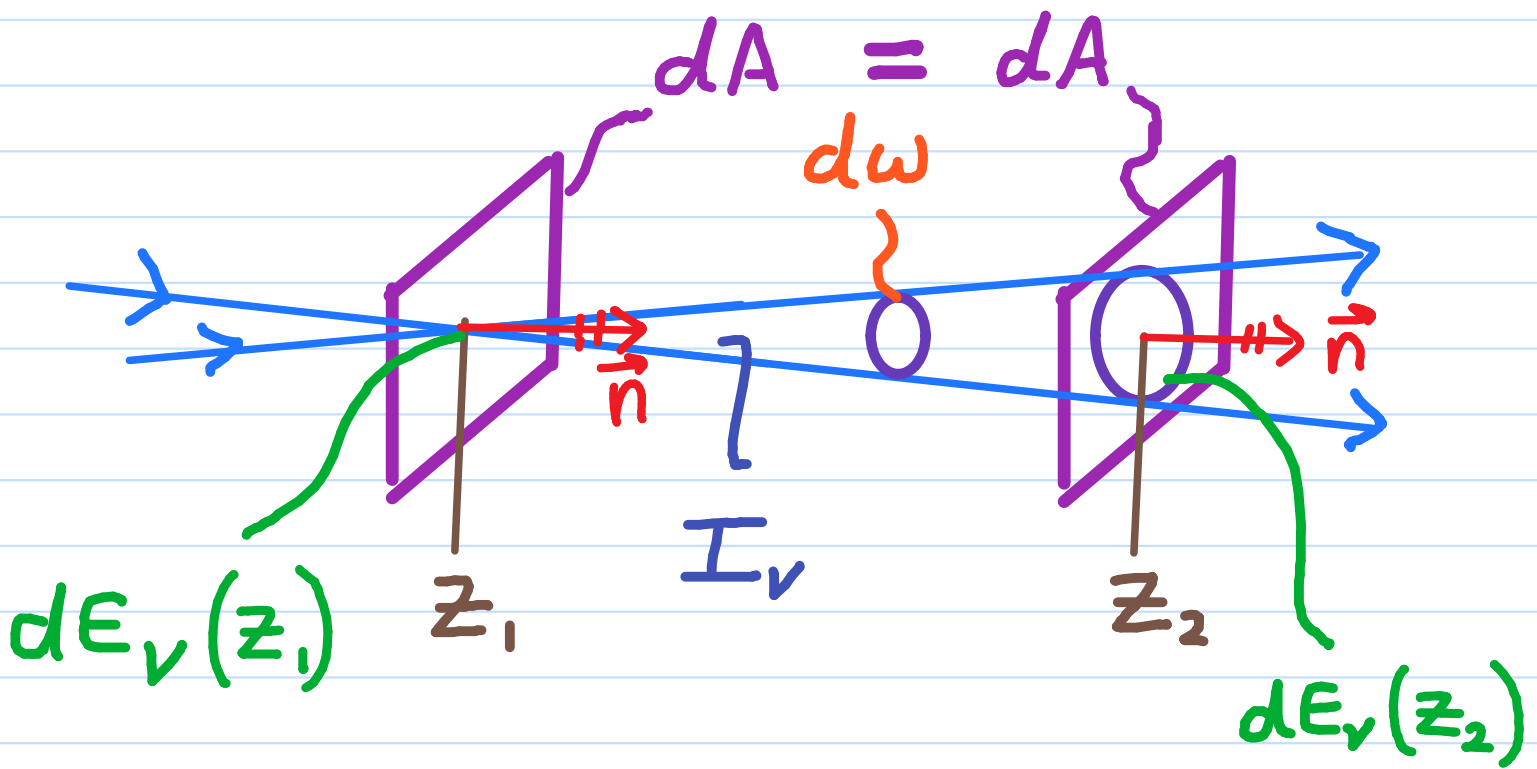


BOLOMETRIC INTENSITY,

$$I(\vec{r}, \vec{l}, t) \quad (\text{erg/s/cm}^2/\text{STER})$$

$$I(\vec{r}, \vec{l}, t) = \int_{\nu=0}^{\infty} I_{\nu}(\vec{r}, \vec{l}, t, \nu) d\nu$$

IN A VACUUM:



IF  $dt_1 = dt_2$  &  $dv_1 = dv_2$ :

CONSERVATION OF E:

$$dE_v(z_2) = dE_v(z_1)$$

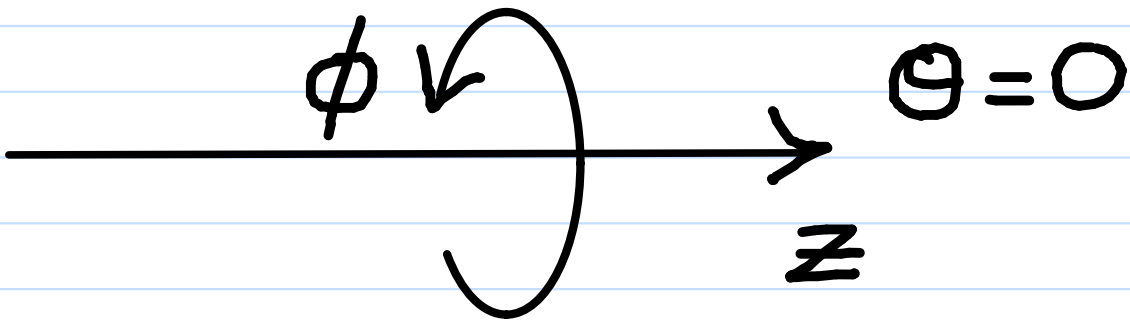
$$\therefore \underline{I_v(z_2) = I_v(z_1)}$$

## SIMPLIFICATIONS:

$$\text{STASIS: } \frac{dI_v(\vec{r}, \vec{l}, v)}{dt} = 0$$

V-DEPENDENCE OBVIOUS

$$\begin{aligned} \therefore I_v(\vec{r}, \vec{l}, t, v) &= I_v(\vec{r}, \vec{l}) \\ &= I_v(x, y, z; \theta, \phi) \end{aligned}$$

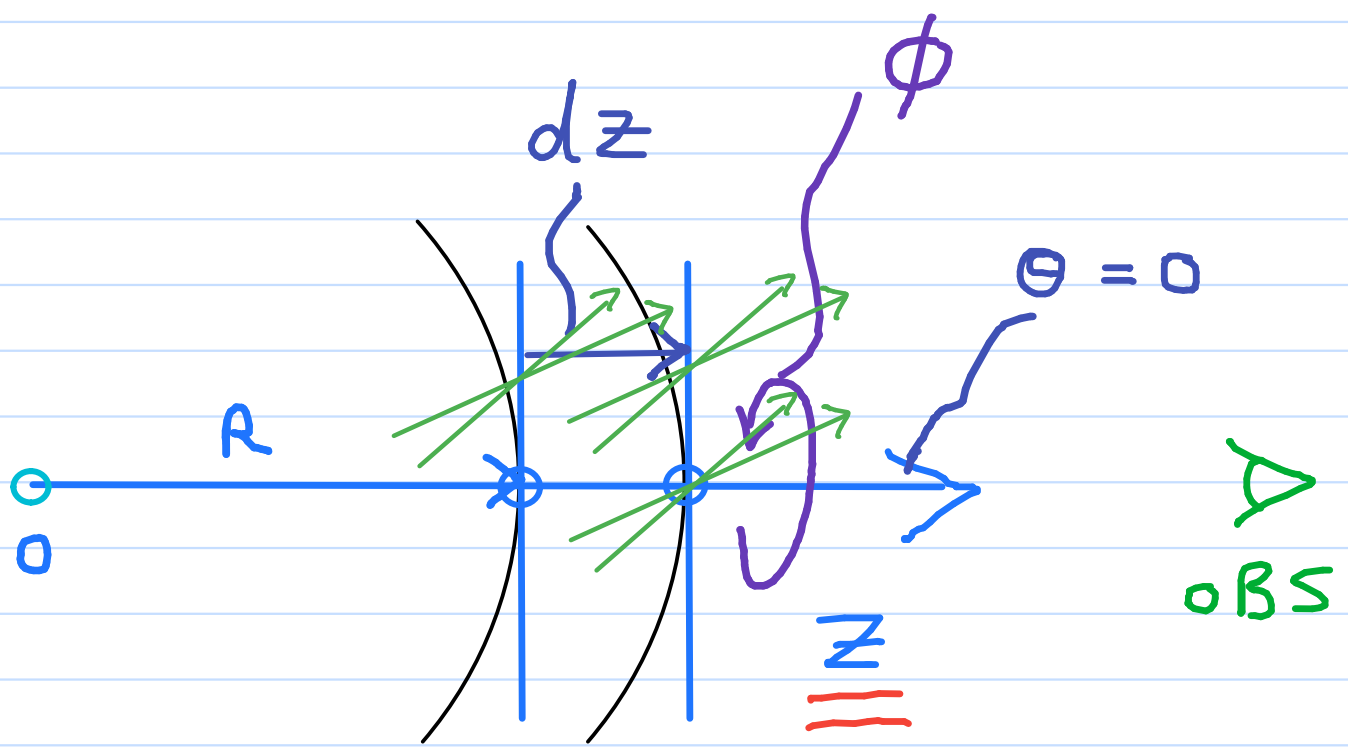


# SIMPLIFICATIONS:

## 1D MODEL:

- PLANE-|| GEOMETRY
- + HORIZONTAL HOMOGENEITY

⇒ AXI-SYMMETRY ABOUT  $z$



$$\begin{aligned}
 I_v(x, y, z; \theta, \phi) &= \underline{I_v(z, \theta)} \\
 &= \underline{I_v(z, \mu)} \sim \cos \theta
 \end{aligned}$$